

## Use of Computer-Generated Animation Films In The Teaching of Physics

Akira Harasima, Graduate School,  
Science Education, ICU

### 1. Introduction

There is no doubt that the best way to teach physics in undergraduate universities as well as secondary schools is to have students conduct experiments themselves or for the teachers to do lecture demonstrations.

However, there are many kinds of physical phenomena in which such direct experiments are very difficult or even impossible to conduct. Among these phenomena we can find, first of all, motions under universal gravitation, if we mean by experiments actual observation of physical phenomena, not model-like experiments. Other examples are motion of projectiles with air resistance, which is, for example, proportional to the square of the velocity, classical Rutherford scattering, motion of a particle under central forces of various kinds, etc.

Fortunately, electronic computers, especially those with plotters or display tubes can provide a good means of generating various kinds of motion with various kinds of parameters and initial conditions.

IBM 1130 Continuous System Modeling Program (CSMP) is most fitted for the purpose. Time marks with adjustable equal time intervals can be put on the orbits. These marks make it

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- 1) The basic idea of this paper was presented at the international conference on physics education, International Union On Pure And Applied Physics, held in Eger, Hungary, Sept. 11-17, 1970. Several films Were also shown at the conference.

convenient for us to make an animated films of the motion.

Color films can provide more information than monochromatic ones. Since it is impossible to make color films from the images on cathode ray display tubes, use was made of plotters, not display tubes, and we resorted to manual labor in order to put colors on the pictures.

## 2. Description of the Procedure

To describe the whole procedure, the case of the motion of an artificial satellite will be shown. The orbit of a satellite can be given analytically. However, the position of the satellite as function of time can only be given implicitly and it is customary that only expressions which give implicitly the relationship between the positions and time are shown. By the use of CSMP one can have the positions of satellite as function of time in the most explicit way.

The gravitational force  $f$  between the earth and the satellite is given by

$$f = G \frac{Mm}{r^2}, \quad (1)$$

where  $G$  is the gravitational constant  $= 6.670 \times 10^{-11} \frac{\text{Nm}^2}{\text{kg}^2}$ ,  $M$  is the mass of the earth,  $m$  the mass of the satellite, and  $r$  is the distance between the earth and the satellite.

With no lack of convenience, we can put

$$GM=1,$$

by changing the values of the units.

The equations of motion of the satellite is given by

$$\begin{aligned} \frac{dx}{dt} &= u, \\ \frac{dy}{dt} &= v, \\ \frac{du}{dt} &= -\frac{x}{(x^2+y^2)^{3/2}}, \\ \frac{dv}{dt} &= -\frac{y}{(x^2+y^2)^{3/2}}. \end{aligned}$$

These equations are first converted into a block diagram, which

can be constructed in a similar way as in cases of analog computers. Each of the blocks is converted into a punched card with the block number, kind of operation, and the input or inputs. The initial conditions and parameter are also given by punched cards.

### 3. An Example: Cospar 1970 11A (Oosumi)

As an example the Cosper 1970 11A, which is also called Oosumi and is the first artificial satellite launched by Japanese scientists is calculated and animated.

According to NASA, the data for this artificial satellite is as follows:

Perigee	328 km
Apogee	5164 km
Period	2 h 24 min
Angle with the equator	30°.1
Eccentricity	0.26502

First the orbit was computed by FORTRAN IV procedure, whose program is shown by Table 1. The fourth order Runge-Kutta approximation method is employed in the integration of the differential equations.

The CSMP configuration and initial conditions-parameters are shown by Table 2. The orbit of Cosper 1970 11A (Oosumi) as drawn on the Plotter sheet is shown by Fig. 1. The motion was then animated and a 8-mm loop film for this satellite was made.

Table 1.

C	MOTION OF ARTIFICIAL SATELLITE FROM THE VALUES OF PERIGEE AND	SATEL 1C
C	APOGEE A, HARASHIMA SEPT. 1969	SATEL 2C
C		
C	OSUMI	
C	PER IS THE MIN DIST OF SATELLITE FROM EARTH SURFACE GIVEN IN KM	SATEL 30
C	APO IS THE MAX DIST OF SATELLITE FROM EARTH SURFACE GIVEN IN KM	SATEL 40
	READ(2,10) PER, APO	
	10 FORMAT(2E20,3)	
	RO = 1 + PER / 6378.	SATEL 70
	R1 = 1 + APO / 6378.	SATEL 80
	VO = ( 2. * R1 / RO / ( RO + R1 ) )**0.5	SATEL 90
	PERIO = 6.2832 * ( 0.5 * ( RO + R1 ) )**1.5	SATEL100
C	H AND PRINT ARE INTEGRATION INTERVAL AND PRINT INTERVAL PRINT IS	SATEL110
C	H AND PRINT ARE INTEGRATION INTERVAL AND PRINT INTERVAL PRINT IS	SATEL110
C	AN INTEGRAL MULTIPLE OF H	SATEL111
	READ(2,20) H, PRINT	
	20 FORMAT ( 2F10.0 )	SATEL130
	WRITE ( 3,100 ) H, PRINT	SATEL140
	100 FORMAT ( 1H0, 'INTEG INTERVAL =', F7.3, 4X, 'PRINT INTERVAL =', F7.3 )	SATEL145
	WRITE(3,200) PER, APO, RO, R1, VO, PERIO	
	200 FORMAT ( 1H0, 2X, 'PER=' , F10.4, 2X, 'APO =', F15.4, 2X, 'RO=' , F10.4, 2X, 'R1=' , F10.4, 2X, 'VO=' , F10.4, 2X, 'PERIO=' , F10.4 )	SATEL160
	1, 'R1=' , F10.4, 2X, 'VO=' , F10.4, 2X, 'PERIO=' , F10.4 )	SATEL161
C	INTEGRATION IS CONDUCTED BY RUNGE-KUTTA FOURTH ORDER APPROXIMATION	SATEL170
	WRITE ( 3,300 )	SATEL180
	300 FORMAT ( 1H0, 13X, 'TIME', 14X, 'X', 14X, 'Y', 14X, 'R' )	SATEL190
	T = 0.	SATEL200
	X = RO	SATEL210
	Y = 0.	SATEL220
	R = RO	SATEL230
	U = 0.	SATEL240
	V = VO	SATEL250
	WRITE ( 3,400 ) T, X, Y, R	SATEL260
	400 FORMAT ( 1H, 10X, F10.4, 3( 5X, F10.7 ) )	SATEL270
	N = PERIO / PRINT + 1.	SATEL280
	M = PRINT / H	SATEL285
	DO 1 I = 1, N	SATEL290
	DO 2 J = 1, M	SATEL300
	D1 = H * U	SATEL310
	E1 = H * V	SATEL320
	F1 = -H * X / ( X**2. + Y**2. )**1.5	SATEL330
	G1 = -H * Y / ( X**2. + Y**2. )**1.5	SATEL340
	D2 = H * ( U + .5 * F1 )	SATEL350
	E2 = H * ( V + .5 * G1 )	SATEL360
	F2 = -H * ( X + .5 * D1 ) / ( ( X + .5 * D1 )**2. + ( Y + .5 * E1 )**2. )**1.5	SATEL370
	G2 = -H * ( Y + .5 * E1 ) / ( ( X + .5 * D1 )**2. + ( Y + .5 * E1 )**2. )**1.5	SATEL380
	D3 = H * ( U + .5 * F2 )	SATEL390
	E3 = H * ( V + .5 * G2 )	SATEL400
	F3 = -H * ( X + .5 * D2 ) / ( ( X + .5 * D2 )**2. + ( Y + .5 * E2 )**2. )**1.5	SATEL410
	G3 = -H * ( Y + .5 * E2 ) / ( ( X + .5 * D2 )**2. + ( Y + .5 * E2 )**2. )**1.5	SATEL420
	D4 = H * ( U + F3 )	SATEL421
	E4 = H * ( V + G3 )	SATEL430
	F4 = -H * ( X + D3 ) / ( ( X + D3 )**2. + ( Y + E3 )**2. )**1.5	SATEL440
	G4 = -H * ( Y + E3 ) / ( ( X + D3 )**2. + ( Y + E3 )**2. )**1.5	SATEL450
	U = U + ( F1 + 2. * F2 + 2. * F3 + F4 ) / 6.	SATEL460
	V = V + ( G1 + 2. * G2 + 2. * G3 + G4 ) / 6.	SATEL470
	X = X + ( D1 + 2. * D2 + 2. * D3 + D4 ) / 6.	SATEL480
	Y = Y + ( E1 + 2. * E2 + 2. * E3 + E4 ) / 6.	SATEL490
	R = SQRT ( X**2. + Y**2. )	SATEL500
	T = T + H	SATEL510
	2 CONTINUE	SATEL520
	WRITE ( 3,400 ) T, X, Y, R	SATEL530
	1 CONTINUE	SATEL540
	STOP	SATEL550
	END	SATEL560
		SATEL570
	FEATURES SUPPORTED	
	ONE WORD INTEGERS	
	EXTENDED PRECISION	
	IOCS	
	CORE REQUIREMENTS FOR	
	COMMON 0 VARIABLES 106 PROGRAM 826	
	END OF COMPILATION	
	// XEQ	SATEL

Table 2.

CONTINUOUS SYSTEM MODELING PROGRAM  
A DIGITAL ANALOG SIMULATOR PROGRAM FOR THE IBM 1130

KEY IN THE 6 DIGITS DATE, 2 FOR MONTH, 2 FOR DAY, 2 FOR YEAR  
022670  
EXTENDED BY T. OSHIMA FOR TOTAL BLOCK NUMBER 150, FUNCTION GENERATOR 6,  
INTEGRATOR 50.

## CONFIGURATION SPECIFICATION

OUTPUT NAME	BLOCK	TYPE	INPUT 1	INPUT 2	INPUT 3
XCODD	1	I	4	0	0
UDOT NEG	2	/	1	13	0
UDOT	3	-	2	0	0
U	4	I	3	0	0
YCODD	5	I	8	0	0
V DOT NEG	6	/	5	13	0
V DOT	7	-	6	0	0
V	8	I	7	0	0
XSQU	9	X	1	1	0
YSQU	10	X	5	5	0
RSQU	11	+	9	10	0
R	12	H	11	0	0
RCUBE	13	X	11	12	0

## INITIAL CONDITIONS AND PARAMETERS

IC/PAR NAME	BLOCK	IC/PAR1	PAR2	PAR3
INIT X	1	1.0000	0.0000	0.0000
INIT U	4	0.0000	0.0000	0.0000
INIT Y	5	0.0000	0.0000	0.0000
INIT V	8	1.0000	0.0000	0.0000

( 0.001 ) INTEGRATION INTERVAL

( 100. ) TOTAL TIME

( 5 ) BLOCK FOR Y-AXIS ( -2.0 ) MINIMUM VALUE ( 2.0 ) MAXIMUM VALUE

( 1 ) BLOCK FOR X-AXIS ( -2.0 ) MINIMUM VALUE ( 2.0 ) MAXIMUM VALUE

PREPARE PLOTTER AND PRESS START  
SET PEN ABOUT ONE INCH FROM RIGHT MARGIN

( 100. ) PRINT INTERVAL

TIME OUTPUT( 1 ) OUTPUT( 5 ) OUTPUT( 4 ) OUTPUT( 8 ) OUTPUT( 12 )

END TERMINATED BY SWITCH 0

Fig 1.

